

# An ergodic theorem on IF sets

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1 Basic notions

2 Ergodic theorem

## Definition (IF-event)

Let  $(\Omega, \mathcal{S})$  be a measurable space. By an IF-event we mean any pair  $A = (\mu_A, \nu_A)$  of  $\mathcal{S}$ -measurable functions, such that  $\mu_A \geq 0, \nu_A \geq 0$  and  $\mu_A + \nu_A \leq 1$ .

The family  $\mathcal{F}$  of all IF-events is ordered by the following way:

$$A \leq B \Leftrightarrow \mu_A \leq \mu_B, \nu_A \geq \nu_B.$$

## Lukasiewicz connectives

We shall use the following Lukasiewicz connectives:

$$\begin{aligned}A \oplus B &= (\mu_A \oplus \mu_B, \nu_A \otimes \nu_B) \\A \otimes B &= (\mu_A \otimes \mu_B, \nu_A \oplus \nu_B),\end{aligned}$$

where the operations  $\oplus, \otimes$  are defined by these equations:

$$\mu_A \oplus \mu_B = (\mu_A + \mu_B) \wedge 1, \quad \mu_A \otimes \mu_B = (\mu_A + \mu_B - 1) \vee 0.$$

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The smallest element in this structure is  $(0, 1)$  and the largest is the element  $(1, 0)$ .

## Definition (The state on $\mathcal{F}$ )

$m : \mathcal{F} \rightarrow [0, 1]$ :

(I)  $m((1, 0)) = 1$ ,  $m((0, 1)) = 0$

(II) if  $A = B \oplus C$ , then  $m(A) = m(B) + m(C)$

(III) if  $A_n \nearrow A$ , then  $m(A_n) \nearrow m(A)$

## Definition (The observable on $\mathcal{F}$ )

$x : \mathcal{B}(R) \rightarrow \mathcal{F}$ :

(i)  $x(R) = (1, 0)$ ,  $x(\emptyset) = (0, 1)$ ;

(ii) if  $A, B \in \mathcal{B}(R)$  and  $A \cap B = \emptyset$ , then

$x(A \cup B) = x(A) \oplus x(B)$ ;

(iii) if  $A_n \in \mathcal{B}(R)$ ,  $A_n \nearrow A$ , then  $x(A_n) \nearrow x(A)$

The composite map  $m \circ x = m_x : \mathcal{B}(R) \rightarrow [0, 1]$  is a probability measure.

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## Definition (The integrable observable)

$\mathcal{F}$  with state  $m$

$x : \mathcal{B}(R) \rightarrow \mathcal{F}$  - observable

The mapping  $x$  is called integrable, if there exists the expected value of the observable defined by the equation:

$$E(x) = \int_R x dm_x(t);$$

where  $m_x : \mathcal{B}(R) \rightarrow [0, 1]$  is composite mapping  $m_x = m \circ x$ .

## Definition (The $m$ -almost everywhere convergence)

$\mathcal{F}$  with a state  $m$

$(y_i)_{i=1}^{\infty}$  - sequence of an observables on the system  $\mathcal{F}$

The sequence converges  $m$ -almost everywhere to 0, if it holds:

$$\lim_{l \rightarrow \infty} \lim_{k \rightarrow \infty} \lim_{i \rightarrow \infty} m \left( \bigwedge_{n=1}^{k+i} y_n \left( -\frac{1}{l}, \frac{1}{l} \right) \right) = 1.$$

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## Definition (The joint observable)

$x, y : \mathcal{B}(R) \rightarrow \mathcal{F}$ -observables

joint observable  $h : \mathcal{B}(R^2) \rightarrow \mathcal{F}$ :

- (i)  $h(R^2) = (1, 0), h(\emptyset) = (0, 1)$ ;
- (ii)  $A \cap B = \emptyset \Rightarrow h(A \cup B) = h(A) \oplus h(B)$ ;
- (iii)  $A_n \nearrow A \Rightarrow h(A_n) \nearrow h(A)$ ;
- (iv)  $h(C \times D) = x(C) \otimes y(D), C, D \in \mathcal{B}(R)$ .

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## Kolmogorov construction

$(x_i)_1^\infty$  - a sequence of observables in the set  $\mathcal{F}$  with a state  $m$   
 $h_n$  - the joint observable of the observables  $x_1, x_2, \dots, x_n, \forall n \in N$   
 $C = \{\pi_n^{-1}(B), B \in \mathcal{B}(R^n), n \in N\}$  - set of all cylinders  
 $\pi_n((u_i)_1^\infty) = (u_1, \dots, u_n)$  - n-th coordinate random vector  
 $(R^N, \sigma(C))$

$$\mathbf{P} \left\{ (u_i)_1^\infty \in R^N; u_1 \in A_1, \dots, u_n \in A_n \right\} = m(h_n(A_1 \times A_2 \times \dots \times A_n))$$

for every  $n \in N$  and every  $A_1, \dots, A_n \in \mathcal{B}(R)$ .

$\forall n \in N: \xi_n : R^N \rightarrow R$  given by  $\xi_n((u_i)_1^\infty) = u_n$  is called n-th coordinate random variable of  $(R^N, \sigma(C), \mathbf{P})$ .

1 Basic notions

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## Definition (The $m$ -state preserving map)

$\mathcal{F}$  with a state  $m$

$$\lambda : \mathcal{F} \rightarrow \mathcal{F}$$

$$\forall A \in \mathcal{F} : m(\lambda(A)) = m(A).$$

## Definition (The ergodic mapping according to observable $x$ )

$$\lambda : \mathcal{F} \rightarrow \mathcal{F}:$$

- (i)  $\lambda$  is  $m$ -state preserving map,
- (ii) if for all  $n \in \mathbb{N}$  the mapping  $h_n : \mathcal{B}(R^n) \rightarrow \mathcal{F}$  is the joint observable of  $x, \lambda \circ x, \dots, \lambda^{n-1} \circ x$  then the following equality holds:

$$m(h_n(A_1 \times A_2 \dots \times A_n)) = m(x_1(A_1) \otimes (\lambda \circ x)(A_2) \otimes \dots \otimes (\lambda^{n-1} \circ x)(A_n)),$$

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## Theorem

$(x_i)_{i=1}^{\infty}$  - a sequence of observables on  $\mathcal{F}$  with state  $m$

$h_n : \mathcal{B}(R^n) \rightarrow \mathcal{F}$  - the joint observable of  $x_1, \dots, x_n$

$P$  = the probability measure generated by the Kolmogorov construction

$\forall n \in N : g_n$  is a Borel function from  $R^n$  to  $R$

The observable  $y_n = g_n(x_1, x_2, \dots, x_n) : \mathcal{B}(R) \rightarrow \mathcal{F}$ :

$$y_n = h_n \circ g_n^{-1}$$

$\pi_n =$  the projection of  $R^N$  to  $R^n : \pi_n((u_i)_{i=1}^{\infty}) = (u_1, u_2, \dots, u_n)$

$\implies$

$$p \circ \pi_n^{-1} \circ g_n^{-1} = m \circ h_n \circ g_n^{-1} = m \circ y_n.$$

In addition: If  $(g_n \circ \pi_n)_{n=1}^{\infty}$  converges  $P$ -almost everywhere to 0

$\implies$

the sequence  $(y_i)_{i=1}^{\infty}$  converges  $m$ -almost everywhere to 0.

## Theorem (The ergodic theorem)

$x$  - integrable observable on  $\mathcal{F}$  with a state  $m$

$\lambda : \mathcal{F} \rightarrow \mathcal{F}$  - ergodic mapping

$$y_n = \frac{1}{n} \sum_{i=0}^{n-1} \lambda^i \circ x - E(x)$$

$\Rightarrow$

converges  $m$ -almost everywhere to 0.