Thirteenth Int. Conf. on IFSs, Sofia, 9-10 May 2009 NIFS Vol. 15 (2009) 2, 18-23

GENERALIZED NET MODEL OF THE INTUITIONISTIC FUZZY FEED FORWARD NEURAL NETWORK

Krasimir Atanasov*, Sotir Sotirov**, Maciej Krawszak ***

*CLBME, Bulgarian Academy of Sciences, Bl. 105, Sofia-1113, BULGARIA, (e-mail: krat@bas.bg)
** Prof. Asen Zlatarov University, Bourgas-8010, BULGARIA, (e-mail: ssotirov@btu.bg)
***Systems Research Institute – Polish Academy of Sciences, Warsaw School of Information technology, Warsaw, Poland, (e-mail: krawczak@ibs.pan.waw.pl)

Abstract

In previous paper we introduced feed forward neural network changed into the definition of the Intuitionistic Fuzzy Logic (IFL). All its parameters used IFL characteristics. In this paper a generalized net model us constructed that introduces work in the IFFFNN.

Index Terms --- Intuitionistic fuzzy set, Feed forward neural network, Generalized nets

Introduction

In a series of papers the process of functioning and the results of the work of different types of neural networks are described by Generalized Nets [10, 12, 14, 15, 16,17]. The possibility for combination of ideas of Neural Networks (NNs) and Intuitionistic Fuzzy Logic (IFL) are discussed in [6, 7, 12]. In [13] we show that the concepts of Feed Forward Neural Networks (FFNNs) and IFL can also be combined.

In this paper we design a Generalized Net model (GN) [2,3] that presents work of the Intuitionistic Fuzzy Feet Forward Neural Network (IFFFNN).

All definitions related to the concept of "IFFFNN" are taken from [13].

Let us have a neuron with R inputs. Let them have intuitionistic fuzzy values $\frac{1}{2}$

$$\langle \mu_{p_1}, \nu_{p_1} \rangle, \langle \mu_{p_2}, \nu_{p_2} \rangle, \dots, \langle \mu_{p_R}, \nu_{p_R} \rangle$$

Let each input p have respective elements $p = \langle \langle \mu_{p_1}, \nu_{p_1} \rangle, \langle \mu_{p_2}, \nu_{p_2} \rangle, ..., \langle \mu_{p_R}, \nu_{p_n} \rangle \rangle$

with weight coefficient from the IFW-matrix $w = \left\langle \left\langle \mu_{w_{1,1}}, \nu_{w_{1,1}} \right\rangle, \left\langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \right\rangle, \dots, \left\langle \mu_{w_{1,R}}, \nu_{w_{1,R}} \right\rangle \right\rangle$.

Thus, the indices in say that weight $\langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \rangle$ represents the connection to the first neuron from the second source.

The transfer functions in neural network are:

- linear transfer function. Output $a = n = \langle \mu_n, \nu_n \rangle$;

- logical sigmoid transfer function with expression:

$$a = \frac{1}{1 + e^{-n}}$$
(1)

According to the IFL

$$F_{sigm} = \left\langle \frac{\varepsilon}{1 + \frac{1}{e^{\mu}}}, \frac{\varepsilon}{1 + \frac{1}{e^{\nu}}} \right\rangle$$
(2)

where

$$\varepsilon = \frac{2}{e+1}.$$
 (3)

A GN-model

All definitions related to the concept "GN" are taken from [2, 3]. The GN, describing the process of the work of the Intuitionistic Fuzzy Feed Forward Neural Network, is shown on Fig.1.

Initially the following tokens enter in the GN:

- in place P - α^{l} -token with initial characteristic

$$x_{0}^{\alpha^{1}} = p^{1} = \left\langle \mu_{w_{1,1}}, \nu_{w_{1,1}} \right\rangle, \left\langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \right\rangle, \dots, \left\langle \mu_{w_{1,R}}, \nu_{w_{1,R}} \right\rangle;$$

- in place $W^{l} - \beta^{l}$ -token with initial characteristic

$$x_{0}^{\beta^{1}} = w^{1} = \left| \left\langle \mu_{w_{1,1}}, \nu_{w_{1,1}} \right\rangle \quad \left\langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \right\rangle \quad \dots \quad \left\langle \mu_{w_{1,R}}, \nu_{w_{1,R}} \right\rangle \right|$$

- in place $b^1 - \gamma^1$ -token with initial characteristic

$$x_0^{\gamma^1} = \left\langle \mu_b, \nu_b \right\rangle;$$

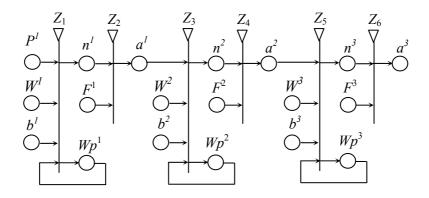


Figure 1. GN of the Intuitionistic Fuzzy Feed Forward Neural Network

- in place F^1 - one δ^1 -token with initial characteristic

 $x_0^{\delta^1} = a = n = \langle \mu_n, \nu_n \rangle$ according to [12];

- in place $W^2 - \beta^2$ -token with initial characteristic

$$x_{0}^{\beta^{2}} = w^{2} = \begin{vmatrix} \langle \mu_{w_{1,1}}, \nu_{w_{1,1}} \rangle & \langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \rangle & \dots & \langle \mu_{w_{1,R}}, \nu_{w_{1,R}} \rangle \\ \langle \mu_{w_{2,1}}, \nu_{w_{2,1}} \rangle & \langle \mu_{w_{2,2}}, \nu_{w_{2,2}} \rangle & & \langle \mu_{w_{2,R}}, \nu_{w_{2,R}} \rangle \\ \dots & \dots & \dots \\ \langle \mu_{w_{S,1}}, \nu_{w_{S,1}} \rangle & \langle \mu_{w_{S,2}}, \nu_{w_{S1,2}} \rangle & & \langle \mu_{w_{S,R}}, \nu_{w_{S,R}} \rangle \end{vmatrix}$$

- in place $b^2 - \gamma^2$ -token with initial characteristic

$$x_0^{\gamma^2} = \left\langle \left\langle \mu_{b_1}, \nu_{b_1} \right\rangle, \left\langle \mu_{b_2}, \nu_{b_2} \right\rangle, \dots, \left\langle \mu_{b_S}, \nu_{b_S} \right\rangle \right\rangle;$$

- in place F^2 one δ^2 -token with initial characteristic using (1), (2) and (3).
- in place $W^3 \beta^3$ -token with initial characteristic $x_{0}^{\beta^{3}} = w^{3} = \left\langle \left\langle \mu_{w_{1,1}}, \nu_{w_{1,1}} \right\rangle, \left\langle \mu_{w_{1,2}}, \nu_{w_{1,2}} \right\rangle, \dots, \left\langle \mu_{w_{1,R}}, \nu_{w_{1,R}} \right\rangle \right\rangle;$
- in place $b^3 \gamma^3$ -token with initial characteristic $x_0^{\gamma^3} = \left\langle \left\langle \mu_{b_1}, \nu_{b_1} \right\rangle, \left\langle \mu_{b_2}, \nu_{b_2} \right\rangle, \dots, \left\langle \mu_{b_S}, \nu_{b_S} \right\rangle \right\rangle;$
- in place F^1 one δ^1 -token with initial characteristic

$$x_0^{\delta^3} = a = n = \langle \mu_n, \nu_n \rangle;$$

The GN is presented by a set of transitions:

$$A = \{ Z_1, Z_2, Z_3, Z_4, Z_5, Z_6 \},\$$

where transitions describe the following processes:

 Z_1 – Calculating influence of the first layer of the IFFNN (n^1) ;

 Z_2 – Calculating the output of the first layer of the IFFNN (a^1);

- Z_3 Calculating influence of the second layer of the IFFNN (n^2);
- Z^4 Calculating influence of the second layer of the IFFNN (a^2); Z^5 Calculating influence of the third layer of the IFFNN (n^3); Z^6 Calculating the output of the third layer of the IFFNN (a^3).

Transitions of the GN-model have the following forms.

$$Z_1 = <\{S_{p^1}, S_{W^1}, S_{b^1}, S_{Wp^1}\}, \{S_{n^1}, S_{Wp^1}\}, R_1, \land (\lor(S_{p^1}, S_{W^1}), \lor(S_{b^1}, S_{Wp^1})) > ,$$

where:

$$\begin{array}{c|cccc} & S_{n^1} & S_{Wp^1} \\ \hline S_{p^1} & False & True \\ R_1 = S_{W^1} & False & True \\ & S_{b^1} & True & False \\ & S_{Wp^1} & True & False \\ \end{array}$$

Tokens α^{l} , β^{l} and γ^{1} union, into the χ^{l} -token according to [13].

$$Z_2 = <\{S_{n^1}, S_{F^1}\}, \{S_{a^1}\}, R_2, \land (S_{n^1}, S_{F^1})>,$$

where:

$$R_{2} = \frac{S_{a^{1}}}{S_{F^{1}}} \frac{True}{True},$$
$$S_{F^{1}} = True$$

Tokens δ^{l} and χ^{l} union into the σ^{l} -token according to [13].

$$Z_3 = <\{S_{a^1}, S_{W^2}, S_{b^2}, S_{Wp^2}\}, \{S_{n^2}, S_{Wp^2}\}, R_3, \land (\lor(S_{a^1}, S_{W^2}), \lor(S_{b^2}, S_{Wp^2}) >, where:$$

$$\begin{array}{c|cccc} S_{n^2} & S_{Wp^2} \\ \hline S_{a^1} & False & True \\ R_3 = S_{W^2} & False & True \\ S_{b^2} & True & False \\ S_{Wp^2} & True & False \\ \end{array}$$

Tokens σ^{l} , β^{2} and γ^{2} union, into the χ^{2} -token according to [13].

$$Z_4 = <\{S_{n^2}, S_{F^2}\}, \{S_{a^2}\}, R_4, \land (S_{n^2}, S_{F^2})>,$$

where:

$$R_{4} = \frac{S_{a^{2}}}{S_{r^{2}}} \frac{S_{a^{2}}}{True},$$
$$S_{F^{2}} = True$$

Tokens δ^2 and χ^2 union into the σ^2 -token, using [13].

$$Z_{5} = <\{S_{a^{2}}, S_{W^{3}}, S_{b^{3}}, S_{Wp^{3}}\}, \{S_{n^{3}}, S_{Wp^{3}}\}, R_{5} \land (\lor(S_{a^{2}}, S_{W^{3}}), \lor(S_{Wp^{3}}, S_{b^{3}})) >,$$

where:

$$\begin{array}{c|cccc} & S_{n^3} & S_{Wp^3} \\ \hline S_{a^2} & False & True \\ R_5 = S_{W^3} & False & True \\ S_{b^3} & True & False \\ S_{Wp^3} & True & False \\ \end{array}$$

Tokens σ^2 , β^3 and γ^3 union, into the χ^3 -token according to [13].

$$Z_6 = < \{S_{n^3}, S_{F^3}\}, \{S_{a^3}\}, R_6, \land (S_{n^3}, S_{F^3}) >,$$

where:

 $R_{6=} \frac{S_{a^3}}{S_{a^3}} \frac{True}{True},$ $S_{a^3} \frac{True}{True}$

Tokens δ^3 and χ^3 union into the σ^3 -token, using [13].

III. Conclusion

The proposed feed forward neural network is changed into the definition of the Intuitionistic Fuzzy Logic (IFL) and Intuitionistic Fuzzy Set (IFS) [1]. All its parameters used IFL characteristics. This paper is generalized net model that introduces work in the IFFFNN.

References

- [1]. Atanassov K., Intuitionistic Fuzzy Sets, Springer Physica-Verlag, Berlin, 1999.
- [2]. Atanassov, K. Generalized nets, World Scientific, Singapore, New Jersey, London 1991.
- [3]. Atanassov, K. On Generalized Nets Theory, "Prof. M. Drinov" Academic Publishing House, Sofia, 2007.
- [4]. Atanassov, K., S. Sotirov, A. Antonov, Generalized net model for parallel optimization of feed-forward neural network, Advanced Studies in Contemporary Mathematics, Vol.15, No. 1 2007, 109-119.
- [5]. Atanassov, K., S. Sotirov, Optimization of a neural network of self-organizing maps type with time-limits by a generalized net, Advanced Studies in Contemporary Mathematics, Vol. 13, No.2, 2006, 213-220.
- [6]. Hadjyisky L., Atanassov K., Generalized net model of the intuitionistic fuzzy neural networks, Advances in Modelling & Analysis, AMSE Press, Vol. 23, 1995, No. 2, 59-64.
- [7]. Hadjyisky L., Atanassov K., Intuitionistic fuzzy model of a neural network, BUSEFAL, Vol. 54, 1993, 36-39.
- [8]. Hagan, M., H. Demuth, M. Beale, Neural Network Design, Boston, MA: PWS Publishing, 1996.
- [9]. Haykin, S. Neural Networks: A Comprehensive Foundation, NY: Macmillan, 1994.
- [10]. Krawczak, M. Generalized Net Models of Systems, Bulletin of Polish Academy of Science, 2003.
- [11]. Krawczak, M. Generalized Net Models of Neural Network Systems, Academic Publishing House, Warsaw, 2003.
- [12]. Kuncheva L., Atanassov K., An intuitionistic fuzzy RBF network, Proceedings of EUFIT'96, Aachen, Sept. 2-5, 1996, 777-781.
- [13]. Sotirov S., Atanassov K., Intuitionistic Fuzzy Feed Forward Neural Network. Cybernetics and Information Technologies, Vol. 9, 2009, No. 2, 71-76.
- [14]. Sotirov, S. Modeling the algorithm Backpropagation for training of neural networks with generalized nets – part 1, Proceedings of the Fourth International Workshop on Generalized Nets, Sofia, 23 September 2003, 61-67.
- [15]. Sotirov, S., Generalized net model of the accelerating backpropagation algorithm, Jangjeon Mathematical Society, 2006, 217-225.

- [16]. Sotirov, S., Krawczak M., Modeling the algorithm backpropagation for training of neural networks with generalized nets – part 2, Issue on Intuitionistic Fuzzy Sets and Generalized Nets, Warsaw, 2003.
- [17]. Sotirov, S., Krawczak M., Modeling the algorithm backpropagation for learning of neural networks with generalized nets part 2, Issue on Intuitionistic Fuzzy Sets and Generalized Nets, Warsaw, 2007, 65-70.