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Intuitionistic fuzzy almost β generalized continuous mappings

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Abstract: In this paper, we introduce the notion of intuitionistic fuzzy almost β generalized continuous mappings. Furthermore we provide some properties of the same set and discuss some fascinating theorems.

Keywords: Intuitionistic fuzzy sets, Intuitionistic fuzzy topology, Intuitionistic fuzzy β generalized closed sets, Intuitionistic fuzzy β generalized open sets, Intuitionistic fuzzy almost β generalized continuous mappings.

AMS Classification: 03E72.

1 Introduction

Atanassov [1] introduced the idea of intuitionistic fuzzy sets using the notion of fuzzy sets. Coker [2] introduced intuitionistic fuzzy topological spaces using the notion of intuitionistic fuzzy sets. Later this was followed by the introduction of intuitionistic fuzzy β generalized closed sets by Saranya, M and Jayanthi, D [9] in 2016 which was simultaneously followed by the introduction of intuitionistic fuzzy β generalized continuous mappings [12] by the same authors. We now extend our idea towards intuitionistic fuzzy almost β generalized continuous mappings and discuss some of their properties.

2 Preliminaries

Definition 2.1 [1]: An *intuitionistic fuzzy set* (IFS for short) A is an object having the form $A = \{\langle x, \mu_A(X), \nu_A(X) \rangle : x \in X\}$, where the functions $\mu_A : X \to [0, 1]$ and $\nu_A : X \to [0, 1]$ denote the degree of membership (namely $\mu_A(X)$) and the degree of non-membership (namely $\nu_A(X)$) of each element $x \in X$ to the set A, respectively, and $0 \le \mu_A(X) + \nu_A(X) \le 1$ for each $x \in X$. Denote by IFS(X), the set of all intuitionistic fuzzy sets in X.

An intuitionistic fuzzy set *A* in *X* is simply denoted by $A = \langle x, \mu_A, \nu_A \rangle$ instead of denoting $A = \{\langle x, \mu_A(X), \nu_A(X) \rangle : x \in X\}.$

Definition 2.2 [1]: Let *A* and *B* be two IFSs of the form $A = \{\langle x, \mu_A(X), \nu_A(X) \rangle : x \in X\}$ and $B = \{\langle x, \mu_B(X), \nu_B(X) \rangle : x \in X\}$. Then,

- (a) $A \subseteq B$ if and only if $\mu_A(X) \le \mu_B(X)$ and $\nu_A(X) \ge \nu_B(X)$ for all $x \in X$,
- (b) A = B if and only if $A \subseteq B$ and $A \supseteq B$,
- (c) $A^c = \{\langle x, v_A(X), \mu_A(X) \rangle : x \in X\},\$
- (d) $A \cup B = \{\langle x, \mu_A(X) \lor \mu_B(X), \nu_A(X) \land \nu_B(X) \rangle : x \in X\},$
- (e) $A \cap B = \{\langle x, \mu_A(X) \land \mu_B(X), \nu_A(X) \lor \nu_B(X) \rangle : x \in X \}.$

The intuitionistic fuzzy sets $0 \sim = \langle x, 0, 1 \rangle$ and $1 \sim = \langle x, 1, 0 \rangle$ are respectively the empty set and the whole set of X.

Definition 2.3 [3]: An *intuitionistic fuzzy topology* (IFT in short) on X is a family τ of IFSs in X satisfying the following axioms:

- (i) $0 \sim$, $1 \sim \in \tau$,
- (ii) $G_1 \cap G_2 \in \tau$ for any $G_1, G_2 \in \tau$,
- (iii) $\cup G_i \in \tau$ for any family $\{G_i : i \in J\} \subseteq \tau$.

In this case the pair (X, τ) is called *intuitionistic fuzzy topological space* (IFTS in short) and any IFS in τ is known as an *intuitionistic fuzzy open set* (IFOS in short) in X. The complement A^c of an IFOS A in an IFTS (X, τ) is called an *intuitionistic fuzzy closed set* (IFCS in short) in X.

Definition 2.4 [8]: An IFS A is said to be an intuitionistic fuzzy dense (IFD for short) in another IFS B in an IFTS (X, τ) , if cl(A) = B.

Definition 2.5 [9]: An IFS A in an IFTS (X, τ) is said to be an *intuitionistic fuzzy* β *generalized closed set* (IF β GCS for short) if β cl $(A) \subseteq U$ whenever $A \subseteq U$ and U is an IF β OS in (X, τ) .

Definition 2.6 [11]: If every IF β GCS in (X, τ) is an IF β CS in (X, τ) , then the space can be called as an intuitionistic fuzzy β generalized $T_{1/2}$ space (IF $\beta_g T_{1/2}$ in short).

Definition 2.7 [12]: A mapping $f: (X, \tau) \to (Y, \sigma)$ is called an *intuitionistic fuzzy* β *generalized continuous* (IF β G continuous for short) **mapping** if $f^{-1}(V)$ is an IF β GCS in (X, τ) for every IFCS V of (Y, σ) .

3 Intuitionistic fuzzy almost β generalized continuous mappings

In this section we introduce intuitionistic fuzzy almost β generalized continuous mappings and investigated some of their properties.

Definition 3.1: A mapping $f: (X, \tau) \to (Y, \sigma)$ is said to be an *intuitionistic fuzzy almost* β *generalized continuous* (IFa β G continuous for short) **mapping** if $f^{-1}(A)$ is an IF β GCS in X for every IFRCS A in Y.

We use the notation $A = \langle x, (\mu_a, \mu_b), (v_a, v_b) \rangle$ instead of $A = \langle x, (a/\mu_a, b/\mu_b), (a/v_a, b/v_b) \rangle$ in the following examples.

Example 3.2: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.3_u, 0.2_v), (0.7_u, 0.8_v) \rangle$. Then $\tau = \{0 \sim, G_1, 1 \sim\}$ and $\sigma = \{0 \sim, G_2, 1 \sim\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \to (Y, \sigma)$ by f(a) = u and f(b) = v.

Then, IF β C(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ /0 $\leq \mu_a + \nu_a \leq 1$ and $0 \leq \mu_b + \nu_b \leq 1$ },

IF β O(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ /0 $\leq \mu_a + \nu_a \leq 1$ and $0 \leq \mu_b + \nu_b \leq 1$ }.

Now $G_2^c = \langle y, (0.7_u, 0.8_v), (0.3_u, 0.2_v) \rangle$ is an IFRCS in Y, Since $cl(int(G_2^c)) = cl(G_2) = G_2^c$. We have $f^{-1}(G_2^c) = \langle x, (0.7_a, 0.8_b), (0.3_a, 0.2_b) \rangle$ is an IFS in X. Now $f^{-1}(G_2^c) \subseteq 1 \sim$. As $\beta cl(f^{-1}(G_2^c)) = f^{-1}(G_2^c) \subseteq 1 \sim$, $f^{-1}(G_2^c)$ is an IF β GCS in X. Thus f is an IF α G continuous mapping.

Remark 3.3: Every IF continuous mapping, IF α continuous mapping, IFS continuous mapping, IFSP continuous mapping, IF β continuous mapping and IF β G continuous mapping are IFa β G continuous mapping but the converses are not true in general.

Example 3.4: In Example 3.2, f is an IFa β G continuous mapping but not an IF continuous mapping, IFS continuous mapping, IF α continuous mapping and IFSP continuous mapping.

Example 3.5: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.6_b), (0.5_a, 0.4_b) \rangle$, $G_2 = \langle y, (0.5_u, 0.3_v), (0.5_u, 0.7_v) \rangle$. Then $\tau = \{0 \sim, G_1, 1 \sim\}$ and $\sigma = \{0 \sim, G_2, 1 \sim\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \to (Y, \sigma)$ by f(a) = u and f(b) = v. The IFS $G_2^c = \langle y, (0.5_u, 0.7_v), (0.5_u, 0.3_v) \rangle$ is an IFCS in Y.

Then, IF β C(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ / $\mu_b < 0.6$ whenever $\mu_a \ge 0.5$, $\mu_a < 0.5$ whenever $\mu_b \ge 0.6$, $0 \le \mu_a + \nu_a \le 1$ and $0 \le \mu_b + \nu_b \le 1$ },

IF β O(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ / either $\mu_a > 0.5$ or $\mu_b > 0.4$, and $0 \le \mu_a + \nu_a \le 1$ and $0 \le \mu_b + \nu_b \le 1$ }.

Now $G_2^c = \langle y, (0.5_u, 0.7_v), (0.5_u, 0.3_v) \rangle$ is an IFRCS in Y, since $\operatorname{cl}(\operatorname{int}(G_2^c)) = \operatorname{cl}(G_2) = G_2^c$. We have $f^{-1}(G_2^c) = \langle x, (0.5_a, 0.7_b), (0.5_a, 0.3_b) \rangle$ is an IFS in X. Now $f^{-1}(G_2^c) \subseteq 1 \sim$. As $\beta \operatorname{cl}(f^{-1}(G_2^c)) = 1 \sim \subseteq 1 \sim$, $f^{-1}(G_2^c)$ is an IF β GCS in X but not an IFPCS in X, since $\operatorname{cl}(\operatorname{int}(f^{-1}(G_2^c))) = \operatorname{cl}(G_1) = 1 \sim \nsubseteq f^{-1}(G_2^c)$. Therefore f is an IF α β G continuous mapping but not an IFP continuous mapping.

Example 3.6: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.7_b), (0.5_a, 0.3_b) \rangle$, $G_2 = \langle y, (0.5_u, 0.2_v), (0.5_u, 0.8_v) \rangle$. Then $\tau = \{0 \sim, G_1, 1 \sim\}$ and $\sigma = \{0 \sim, G_2, 1 \sim\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \to (Y, \sigma)$ by f(a) = u and f(b) = v.

Then, IF β C(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ / provided either $\mu_b < 0.7$ whenever $\mu_a \ge 0.5$ or $\mu_a < 0.5$ whenever $\mu_b \ge 0.7$, $0 \le \mu_a + \nu_a \le 1$ and $0 \le \mu_b + \nu_b \le 1$ }.

IF β O(X) = {0~, 1~, $\mu_a \in [0, 1], \mu_b \in [0, 1], v_a \in [0, 1], v_b \in [0, 1] / either <math>\mu_a > 0.5$ or $\mu_b > 0.3$, $0 \le \mu_a + v_a \le 1$ and $0 \le \mu_b + v_b \le 1$ }.

Now $G_2^c = \langle y, (0.5_u, 0.8_v), (0.5_u, 0.2_v) \rangle$ is an IFRCS in Y, Since $\operatorname{cl}(\operatorname{int}(G_2^c)) = \operatorname{cl}(G_2) = G_2^c$. We have $f^{-1}(G_2^c) = \langle x, (0.5_a, 0.8_b), (0.5_a, 0.2_b) \rangle$ is an IFS in X. Now $f^{-1}(G_2^c) \subseteq 1 \sim$. As $\beta \operatorname{cl}(f^{-1}(G_2^c)) = 1 \sim \subseteq 1 \sim$, $f^{-1}(G_2^c)$ is an IF β GCS in X but not an IF β CS in X, since $\operatorname{int}(\operatorname{cl}(\operatorname{int}(f^{-1}(G_2^c)))) = \operatorname{int}(\operatorname{cl}(G_1)) = \operatorname{int}(1 \sim) = 1 \sim \not\subseteq f^{-1}(G_2^c)$. Therefore f is an IF α GC continuous mapping but not an IF β continuous mapping.

Example 3.7: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.7_b), (0.2_a, 0.1_b) \rangle$, $G_2 = \langle y, (0.2_u, 0.2_v), (0.5_u, 0.8_v) \rangle$ and $G_3 = \langle y, (0.2_u, 0.2_v), (0.5_u, 0.6_v) \rangle$. Then $\tau = \{0 \sim, G_1, 1 \sim\}$ and $\sigma = \{0 \sim, G_2, G_3, 1 \sim\}$ are IFTs on X and Y, respectively. Define a mapping $f: (X, \tau) \to (Y, \sigma)$ by f(a) = u and f(b) = v.

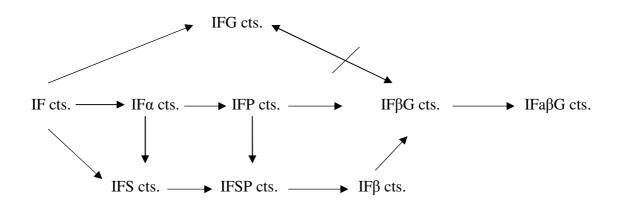
Then, IF β C(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ / either $\mu_a < 0.5$ or $\mu_b < 0.7$, $\leq \mu_a + \nu_a \leq 1$ and $0 \leq \mu_b + \nu_b \leq 1$ }.

IF β O(X) = {0 \sim , 1 \sim , $\mu_a \in [0, 1]$, $\mu_b \in [0, 1]$, $\nu_a \in [0, 1]$, $\nu_b \in [0, 1]$ / either $\mu_a > 0.2$ or $\mu_b > 0.1$, $0 \le \mu_a + \nu_a \le 1$ and $0 \le \mu_b + \nu_b \le 1$ }.

Now $G_3^c = \langle y, (0.5_u, 0.6_v), (0.2_u, 0.2_v) \rangle$ is an IFRCS in Y, Since $cl(int(G_3^c)) = cl(G_3) = G_3^c$. We have $f^{-1}(G_3^c) = \langle x, (0.5_a, 0.6_b), (0.2_a, 0.2_b) \rangle \subseteq G_1$ and $\beta cl(f^{-1}(G_3^c)) = f^{-1}(G_3^c) \subseteq G_1$. Hence $f^{-1}(G_3^c)$ is an IF β GCS in X. Thus f is an IF α β G continuous mapping.

We have $G_2^c = \langle y, (0.5_u, 0.8_v), (0.2_u, 0.2_v) \rangle$ is IFCS in Y. We have $\beta \operatorname{cl}(f^{-1}(G_2^c)) = 1 \sim \not\subseteq G_1$. Hence $f^{-1}(G_2^c)$ is not an IF β GCS in X. Thus f is not an IF β G continuous mapping.

The relation between various types of intuitionistic fuzzy continuity is given in the following diagram. In this diagram 'cts.' means continuous.



The reverse implications are not true in general in the above diagram.

Theorem 3.8: A mapping $f: (X, \tau) \to (Y, \sigma)$ is an IFa β G continuous mapping if and only if the inverse image of each IFROS in Y is an IF β GOS in X . Proof: (Necessity): Let A be an IFROS in Y . This implies A^c is IFRCS in Y . Since f is an IFa β G continuous mapping, $f^{-1}(A^c)$ is an IF β GCS in X . Since $f^{-1}(A^c) = (f^{-1}(A))^c$, $f^{-1}(A)$ is an IF β GOS in Y .
IFβGOS in <i>X</i> . (Sufficiency): Let <i>A</i> be an IFRCS in <i>Y</i> . This implies A^c is an IFROS in <i>Y</i> . By hypothesis, $f^{-1}(A^c)$ is an IFβGOS in <i>X</i> . Since $f^{-1}(A^c) = (f^{-1}(A))^c$, $f^{-1}(A)$ is an IFβGCS in <i>X</i> . Hence <i>f</i> is an IFaβG continuous mapping.
Theorem 3.9: Let $p_{(\alpha,\beta)}$ be an intuitionistic fuzzy point (IFP in short) [4] in X . A mapping $f:(X,\tau)\to (Y,\sigma)$ is an IFa β G continuous mapping if for every IFOS A in Y with $p_{(\alpha,\beta)}\in A$, there exists an IFOS B in X with $p_{(\alpha,\beta)}\in B$ such that $f^{-1}(A)$ is intuitionistic fuzzy dense [8] in B .
<i>Proof</i> : Let A be an IFROS in Y . Then A is an IFOS in Y . Let $p_{(\alpha,\beta)} \in A$, then there exists an IFOS B in X such that $p_{(\alpha,\beta)} \in B$ and $cl(f^{-1}(A)) = B$. Therefore $cl(f^{-1}(A)) = B$ is also an IFOS in X and $int(cl(f^{-1}(A))) = cl(f^{-1}(A))$. Now $f^{-1}(A) \subseteq cl(f^{-1}(A)) = int(cl(f^{-1}(A))) \subseteq cl(int(cl(f^{-1}(A))))$. This implies $f^{-1}(A)$ is an
IF β OS in X and hence an IF β GOS in X . Thus f is an IFa β G continuous mapping.
Theorem 3.10: Let $f:(X, \tau) \to (Y, \sigma)$ be a mapping. If $f^{-1}(\beta \operatorname{int}(B)) \subseteq \beta \operatorname{int}(f^{-1}(B))$ for every IFS B in Y , then f is an IFa β G continuous mapping. $Proof$: Let $B \subseteq Y$ be an IFROS. By hypothesis, $f^{-1}(\beta \operatorname{int}(B)) \subseteq \beta \operatorname{int}(f^{-1}(B))$. Since B is IFROS, it is an IF β OS in Y . Therefore $\beta \operatorname{int}(B) = B$. Hence $f^{-1}(B) = f^{-1}(\beta \operatorname{int}(B)) \subseteq \beta \operatorname{int}(f^{-1}(B)) \subseteq f^{-1}(B)$. This implies $f^{-1}(B)$ is an IF β OS in X and hence $f^{-1}(B)$ is an IF β GOS [10] in X . Thus f is an IFa β G continuous mapping.
Remark 3.11: The converse of the above theorem is true if $B \subseteq Y$ is an IFROS and X is an IF $\beta_g T_{1/2}$ space. <i>Proof</i> : Let f be an IF $a\beta G$ continuous mapping. Let B be an IFROS in Y then by hypothesis $f^{-1}(B)$ is an IF βGOS in X . Since X is an IF $\beta_g T_{1/2}$ space, $f^{-1}(B)$ is an IF βGOS in X . Therefore, $f^{-1}(\beta int(B)) \subseteq f^{-1}(B) = \beta int(f^{-1}(B))$.
Theorem 3.12: Let $f: (X, \tau) \to (Y, \sigma)$ be a mapping. If $\beta \operatorname{cl}(f^{-1}(B)) \subseteq f^{-1}(\beta \operatorname{cl}(B))$ for every IFS B in Y , then f is an IFa β G continuous mapping. $Proof$: Let $B \subseteq Y$ be an IFRCS. By hypothesis, $\beta \operatorname{cl}(f^{-1}(B)) \subseteq f^{-1}(\beta \operatorname{cl}(B))$. Since B is an IFRCS, it is an IF β CS in Y . Therefore $\beta \operatorname{cl}(B) = B$. Hence $f^{-1}(B) = f^{-1}(\beta \operatorname{cl}(B)) \supseteq \beta \operatorname{cl}(f^{-1}(B)) \supseteq f^{-1}(B)$. This implies $f^{-1}(B)$ is an IF β CS in X and hence $f^{-1}(B)$ is an IF β GCS [9] in X . Thus f is an IFa β G continuous mapping.
Remark 3.13: The converse of the above theorem is true if $B \subseteq Y$ is an IFRCS and X is an IF $\beta_g T_{1/2}$ space. <i>Proof</i> : Let f be an IF $a\beta G$ continuous mapping. Let B be an IFRCS in Y then by hypothesis $f^{-1}(B)$ is an IF βGCS in X . Since X is an IF $\beta_g T_{1/2}$ space, $f^{-1}(B)$ is an IF βCS in X . Therefore, $\beta \operatorname{cl}(f^{-1}(B)) = f^{-1}(B) \subseteq f^{-1}(\beta \operatorname{cl}(B))$.

Definition 3.14:	Let A	be an	IFS i	n an	IFTS	(X,	τ).	Then	the β	generalized	interior	and f
generalized closus	re of A	are de	fined	as								

 β gint(A) = \cup {G / G is an IF β GOS in X and $G \subseteq A$ }, β gcl(A) = \cap {K / K is an IF β GCS in X and $A \subseteq K$ }.

Note that for any IFS A in (X, τ) , we have $\beta gcl(A^c) = (\beta gint(A))^c$ and $\beta gint(A^c) = (\beta gcl(A))^c$.

Remark 3.15: If an IFS A in an IFTS (X, τ) is an IF β GCS in X, then β gcl(A) = A. But the converse may not be true in general, since intersection does not exist in IF β GCS [9].

Remark 3.16: If an IFS A in an IFTS (X, τ) is an IF β GOS in X, then β gint(A) = A. But the converse may not be true in general, since union does not exist in IF β GOS [10].

Theorem 3.17: Let $f: (X, \tau) \to (Y, \sigma)$ be a mapping. If f is an IFa β G continuous mapping, then $\beta \gcd(f^{-1}(A)) \subseteq f^{-1}(\operatorname{cl}(A))$ for every IF β OS A in Y.

Proof: Let A be an IF β OS in Y. Then cl(A) is an IFRCS in Y [8]. By hypothesis $f^{-1}(cl(A))$ is an IF β GCS in X. Then β gcl($f^{-1}(cl(A))$) = $f^{-1}(cl(A))$. Now β gcl($f^{-1}(A)$) $\subseteq \beta$ gcl($f^{-1}(cl(A))$) = $f^{-1}(cl(A))$. That is β gcl($f^{-1}(A)$) $\subseteq f^{-1}(cl(A))$.

Theorem 3.18: Let $f: (X, \tau) \to (Y, \sigma)$ be a mapping. If f is an IFa β G continuous mapping, then $\beta \gcd(f^{-1}(\operatorname{cl}(A))) = f^{-1}(\operatorname{cl}(\beta \operatorname{int}(A)))$ for every IF β OS A in Y.

Proof: Let A be an IF β OS in Y. Then β int(A) = A and cl(A) is an IFRCS in Y [8]. By hypothesis $f^{-1}(\text{cl}(A))$ is an IF β GCS in X. Then β gcl($f^{-1}(\text{cl}(A))) = f^{-1}(\text{cl}(A)) \subseteq f^{-1}(\text{cl}(\beta))$.

Theorem 3.19: Let $f: (X, \tau) \to (Y, \sigma)$ be a mapping where X is an IF $\beta_g T_{1/2}$ space. If f is an IF βG continuous mapping, then int(cl(int($f^{-1}(B)$)) $\subseteq f^{-1}(\beta cl(B))$ for every IFRCS B in Y.

Proof: Let $B \subseteq Y$ be an IFRCS. By hypothesis, $f^{-1}(B)$ is an IF β GCS in X. Since X is an IF β gT_{1/2} space, $f^{-1}(B)$ is an IF β CS in X. Therefore β cl $(f^{-1}(B)) = f^{-1}(B)$.

Now $\operatorname{int}(\operatorname{cl}(\operatorname{int}(f^{-1}(B)))) \subseteq f^{-1}(B) \cup \operatorname{int}(\operatorname{cl}(\operatorname{int}(f^{-1}(B)))) \subseteq \beta \operatorname{cl}(f^{-1}(B)) = f^{-1}(B) = f^{-1}(\beta \operatorname{cl}(B)).$ Hence $\operatorname{int}(\operatorname{cl}(\operatorname{int}(f^{-1}(B)))) \subseteq f^{-1}(\beta \operatorname{cl}(B)).$

Theorem 3.20: Let $f: (X, \tau) \to (Y, \sigma)$ be a mapping where X is an IF $\beta_g T_{1/2}$ space. If f is an IF $\alpha\beta G$ continuous mapping, then $f^{-1}(\beta \operatorname{int}(B)) \subseteq \operatorname{cl}(\operatorname{int}(\operatorname{cl}(f^{-1}(B))))$ for every IFROS B in Y. *Proof*: This theorem can be easily proved by taking complement in Theorem 3.19.

Theorem 3.21: Let $f: (X, \tau) \to (Y, \sigma)$ be an IFa β G continuous mapping and $g: (Y, \sigma) \to (Z, \delta)$ is an IF continuous mapping then $g: (X, \tau) \to (Z, \delta)$ is an IFa β G continuous mapping. *Proof*: Let V be an IFRCS in Z. Since every IFRCS is an IFCS in Z. Then $g^{-1}(V)$ is an IFCS in

Y. Since *f* is an IF β G continuous mapping, $f^{-1}(g^{-1}(V))$ is an IF β GCS in *X*. Hence $g \circ f$ is an IF $\alpha\beta$ G continuous mapping.

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