

Conditional probability on IF-events

Veronika Valenčáková

Faculty of Natural Sciences

Matej Bel University

Tajovského 40

SK-974 01 Banská Bystrica

valencak@fpv.umb.sk

Abstract

Probability on collections of IF-sets can be considered as a generalization of the classical probability theory on σ -algebras of sets. The aim of this contribution is to formulate the version of the conditional probability on IF-events and show its properties. The paper is based on the idea for Łukasiewicz implication, but now there are a lot of different implications in the theory of IF-sets.

Keywords: IF-event, conditional probability.

1 Introduction

The theory of Intuitionistic Fuzzy Sets (IF-sets) was introduced by ATANASSOV. We recall that an IF-set is a couple of functions (μ, ν) with values in the unit interval, such that $\mu + \nu \leq 1$.

We consider a **Łukasiewicz tribe** with product (denoted by \mathcal{T}), which is a non empty set of functions $f : \Omega \rightarrow [0, 1]$ satisfying the following conditions:

- (i) if $f \in \mathcal{T}$ then $1 - f \in \mathcal{T}$,
- (ii) if $f, g \in \mathcal{T}$ then $f \oplus g \in \mathcal{T}$,
- (iii) if $f_n \in \mathcal{T} (n = 1, 2, \dots)$, $f_n \nearrow f$ then $f \in \mathcal{T}$,
- (iv) if $f, g \in \mathcal{T}$ then $f.g \in \mathcal{T}$.

The well-known Łukasiewicz operations \oplus, \odot on \mathcal{T} are given by

$$f \oplus g = \min(f + g, 1) = (f + g) \wedge 1, \quad f \odot g = \max(f + g - 1, 0) = (f + g - 1) \vee 0.$$

Denote by \mathcal{F} the family of IF-events: $\mathcal{F} = \{(f, g); f, g \in \mathcal{T}, f + g \leq 1\}$ together with the operations \oplus, \odot :

$$(f_1, g_1) \oplus (f_2, g_2) = (f_1 \oplus f_2, g_1 \odot g_2) = ((f_1 + f_2) \wedge 1, (g_1 + g_2 - 1) \vee 0),$$

$$(f_1, g_1) \odot (f_2, g_2) = (f_1 \odot f_2, g_1 \oplus g_2) = ((f_1 + f_2 - 1) \vee 0, (g_1 + g_2) \wedge 1),$$

$$\neg(f, g) = (1 - f, 1 - g).$$

We define an order on \mathcal{F} by $(f_1, g_1) \leq (f_2, g_2) \iff f_1 \leq f_2$ and $g_1 \geq g_2$, and recall that

$$(f_n, g_n) \nearrow (f, g) \iff f_n \nearrow f, g_n \searrow g.$$

The **product operation** on \mathcal{F} is a binary operation \cdot defined by

$$(f_1, g_1) \cdot (f_2, g_2) = (f_1 \cdot f_2, 1 - (1 - g_1) \cdot (1 - g_2)) = (f_1 \cdot f_2, g_1 + g_2 - g_1 \cdot g_2).$$

Proposition 1 (LENDELOVÁ [6]) *The product operation defined of \mathcal{F} satisfies following conditions:*

- (i) $(1, 0) \cdot (f, g) = (f, g)$ for each $(f, g) \in \mathcal{F}$,
- (ii) operation \cdot is commutative and associative,
- (iii) if $(f_1, g_1), (f_2, g_2) \in \mathcal{F}$ and $(f_1, g_1) \odot (f_2, g_2) = (0, 1)$, then

$$(f_3, g_3) \cdot ((f_1, g_1) \oplus (f_2, g_2)) = ((f_3, g_3) \cdot (f_1, g_1)) \oplus ((f_3, g_3) \cdot (f_2, g_2))$$

and

$$((f_3, g_3) \cdot (f_1, g_1)) \odot ((f_3, g_3) \cdot (f_2, g_2)) = (0, 1)$$

for each $(f_3, g_3) \in \mathcal{M}$,

- (iv) if $(f_{1n}, g_{1n}), (f_{2n}, g_{2n}) \in \mathcal{F}$ and $(f_{1n}, g_{1n}) \searrow (0, 1), (f_{2n}, g_{2n}) \searrow (0, 1)$, then $(f_{1n}, g_{1n}) \cdot (f_{2n}, g_{2n}) \searrow (0, 1)$.

Proof. See [6], Theorem 1.

2 Conditional probability

Definition 1 A *state* on \mathcal{F} is a mapping $m : \mathcal{F} \longrightarrow [0, 1]$, which satisfies the following conditions:

1. $m(1, 0) = 1$,
2. if $(f_1, g_1) \oplus (f_2, g_2) \leq (1, 0)$ then $m((f_1, g_1) \oplus (f_2, g_2)) = m(f_1, g_1) + m(f_2, g_2)$,
3. if $(f_n, g_n) \nearrow (f, g)$ then $m(f_n, g_n) \nearrow m(f, g)$.

Remark The condition 2. in previous *Definition* can be equivalently written as follows:

$$\text{if } (f_1, g_1) \leq \neg(f_2, g_2) \text{ then } m((f_1, g_1) \oplus (f_2, g_2)) = m(f_1, g_1) + m(f_2, g_2).$$

By induction is easy to prove that

$$\text{if } \bigoplus_{n=1}^k (f_n, g_n) \leq (1, 0) \text{ then } m(\bigoplus_{n=1}^k (f_n, g_n)) = \sum_{n=1}^k m(f_n, g_n).$$

Definition 2 Denote by $\mathcal{B}(R)$ the Borel σ -algebra. An **observable** on \mathcal{F} is a mapping $y : \mathcal{B}(R) \longrightarrow \mathcal{F}$ satisfying the following conditions:

1. $y(R) = (1, 0)$,
2. if $A \cap B = \emptyset$ then $y(A) \odot y(B) = (0, 1)$ and $y(A \cup B) = y(A) \oplus y(B)$,
3. if $A_n \nearrow A$ then $y(A_n) \nearrow y(A)$.

Definition 3 If m is a state and y is an observable on \mathcal{F} , then the **probability distribution of y** is the mapping $m_y : \mathcal{B}(R) \longrightarrow [0, 1]$ given by the formula

$$m_y(A) = m(y(A)).$$

Theorem 1 There exists an integrable function $\varphi : R \rightarrow R$ such that

$$\int_a^b \varphi \, d\mu_{\mathcal{F}} = m((f, g) \cdot y([a, b]))$$

holds for any interval $[a, b]$.

Proof.

Existence of function φ will be proved by with help of embedding \mathcal{F} into MV-algebra. Existence of function $p : R \rightarrow R$ satisfying the condition

$$\int_B p \, dm_y = m((f, g) \cdot y(B))$$

(for $(f, g) \in \mathcal{M}$, $m : \mathcal{M} \rightarrow [0, 1]$, $y : \mathcal{B}(R) \rightarrow \mathcal{M}$) was proved in [9].

The considered MV-algebra induced by IF-events was $(\mathcal{M}, \oplus, \odot, \neg, \mathbf{0}, u)$, where

$$\begin{aligned} \mathcal{M} &= \{(f, g); f, g \in \mathcal{T}, \mathcal{T}\}, \\ (f_1, g_1) \oplus (f_2, g_2) &= ((f_1 + f_2) \wedge 1, (g_1 + g_2 - 1) \vee 0), \\ (f_1, g_1) \odot (f_2, g_2) &= ((f_1 + f_2 - 1) \vee 0, (g_1 + g_2) \wedge 1), \\ \neg(f, g) &= (1 - f, 1 - g), \\ \mathbf{0} &= (0, 1), \\ u &= (1, 0). \end{aligned}$$

From the facts:

- family \mathcal{F} can be embedded into \mathcal{M} ,
- there exists one-to-one correspondence between state (probability) on \mathcal{M} and state (probability) on \mathcal{F} ,

is clear, that the existence of the function φ follows from the existence of version of the conditional probability on MV-algebra \mathcal{M} induced by IF-events.

Definition 4 Let $(f, g) \in \mathcal{F}$ and $y : \mathcal{B}(R) \rightarrow \mathcal{F}$ be an observable. A function $p((f, g)|y) : R \rightarrow R$ is a version of the **conditional probability** of (f, g) with respect to y , if

$$\int_B p((f, g)|y) dm_y = m((f, g) \cdot y(B))$$

for every $B \in \mathcal{B}(R)$.

Properties of conditional probability (listed in next *Proposition*) follow immediately from the properties of conditional probability defined on MV-algebra \mathcal{M} .

Proposition 2 Let y be an observable, $(f, g) \in \mathcal{F}$. Then $p((f, g)|y)$ has the following properties:

1. $p((0, 1)|y) = 0$, $p((1, 0)|y) = 1$ m_y -almost everywhere,
2. $0 \leq p((f, g)|y) \leq 1$ m_y -almost everywhere,
3. if $\widehat{+}_{n=1}^k (f_n, g_n) \leq (1, 0)$ then $p([\widehat{+}_{n=1}^k (f_n, g_n)]|y) = \sum_{n=1}^k p((f_n, g_n)|y)$ m_y -almost everywhere,
4. if $(f_n, g_n) \nearrow (f, g)$ then $p((f_n, g_n)|y) \nearrow p((f, g)|y)$ m_y -almost everywhere.

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